A Smart Transformer-Rectifier Unit for the More Electric Aircraft

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Abstract-In the framework of the More Electric Aircraft (MEA), an efficient and flexible power distribution system is of paramount importance. Considering the presence of both AC and DC loads at multiple voltage levels, the distribution system of the most modern aircrafts is intrinsically hybrid. In this scenario, the different buses are connected by AC/DC converters. The simplest approach is to use a Transformer-Rectifier Unit (TRU) based on a low-frequency transformer followed by passive rectifiers to perform the AC/DC conversion. This solution, however, is intrinsically uni-directional, introduces current harmonics in the AC side and can have a considerable size. This paper proposes the use of a Smart-TRU, based on a Cascaded H-Bridge topology and a multi-port DC/DC converter, to solve the issues of the traditional TRU, increasing the controllability of the system. Experiments show how the proposed STRU is resilient to faults in the AC side.

I. INTRODUCTION

Transportation electrification has been the object of an intense research activity by both industry and academia, following the pursuit of a more sustainable transport and a higher efficiency. Regarding the aircraft transportation, the More Electric Aircraft (MEA) framework advocates for an increase electrification of the airplanes and for the gradual substitution of hydraulic subsystems for maintenance and efficiency purposes. Conventional aircrafts adopt bleed valves in the jet engine for the cabin pressurization and environment control, this leads to a decrease of the engine efficiency. Newer aircrafts have eliminated the bleed valves [1], choosing for big electrical generators that provide the electrical power used to drive the compressor and the oil and fuel pumps [2]. A futuristic concept envisages the substitution of the oil distribution with electromechanical actuators or even fully electrical actuators, further increasing the electric power requirements.

Electrical generators have a natural three-phase sinusoidal voltage, but many loads, in particular the avionics, are DC loads. This call for the need of Transformer-Rectifier Units (TRU) [3], to realize the DC bus. This paper analyzes the possibility offered by multi-port converters for the realization of smart TRUs (STRU) to give additional services to the aircraft power system.

The paper is organized as follows, section II describes the possible electrical distribution system paradigms, section III describes the smart TRUs topologies, section IV presents the experimental results related to a fault in the AC side and section V draws the conclusion.

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II. ELECTRICAL POWER DISTRIBUTION SYSTEM (EPDS)

There are several standards for the electrical distribution system of today's aircraft, mainly referring to the MIL-STD-704. Considering the actual trends of electrification, a voltage increase (bipolar distribution) is also envisaged.

The possible voltage and frequency levels are:

- 28 V DC low power loads/avionics on large aircraft and complete electrical system on small aircraft.
- 270 V DC (bipolar $\pm 135V$) military aircrafts and some subsystems on some larger aircrafts.
- 115 V AC at 400 Hz larger loads on large civilian aircrafts.
- 115 V AC variable frequency from 360 Hz to 800 Hz.
- 540 V DC (bipolar $\pm 270V$).
- 230 V AC at 400 Hz.

Considering the different load mix, AC (fuel and oil pumps, fans) and DC (actuators, avionics, batteries) co-exist, where generators and an auxiliary power unit (APU) powers the electrical bus. In [4], different architectures for the hybrid EPDS have been analyzed, drawing the conclusion that a full-DC implementation with AC/DC rectifiers for the generators without the variable-frequency three-phase distribution is the most efficient in terms of weight. In Fig. 1a, the generators are feeding a three-phase AC bus with variable frequency. The control of the excitation regulates a constant voltage amplitude. TRU are used to provide the HVDC bus at 270V. A switching matrix allows for the connection of the APU to the other bus bars. In the case of a fault in one engine, the bus bars can also be connected to keep the EPDS operational. In Fig. 1b, the generators are directly connected to AC/DC converters that provide the DC bus. AC loads are connected to the DC distribution via a DC/AC inverter.

III. POWER CONVERTER DESCRIPTION

The quadruple active bridge converter has been proposed to be used in aircraft systems in several works [5]–[7]. Its multiport characteristic made it the suitable candidate to interface different power sources and to guarantee the power exchange among the DC buses.

Fig. 2 shows the schematic of the QAB. Although several modulation strategies are feasible [8], the phase-shift modulation, where each H-bridge generates a square wave with 50



Fig. 1: Example of an hybrid electrical power distribution systems with AC (a) and DC (b) distribution.

% duty cycle and the phase-shift between the ports regulates the power transfer.

Equation (1) describes the overall power that is processed by a single port, where n_{ij} is the turn ratio between the two ports, L_{ij} is the equivalent inductance from the two ports and d_{ij} is the phase shift angle normalized to 2π .

$$P_{i} = \sum_{j \neq i} \frac{n_{ij} V_{i} V_{j}}{L_{ij} f_{sw}} d_{ij} \left(1 - 2d_{ij}\right)$$
(1)

The Cascaded H-bridge has been extensively adopted for medium-voltage power converters due to its modularity and the possibility to adopt low-voltage devices. Other characteristics, like a reduced output harmonic distortion and ease of control contributed to its success. One of its biggest disadvantages, however, is the necessity to provide isolated DC Links to all the H-bridge cells and the need for the isolating transformer to be designed for the full medium voltage.

If the CHB is adopted for LV applications, this constraint of the transformer isolation is not anymore relevant and the transformer can be optimized for efficiency and power density (i.e., primary and secondary windings can be overlapped to minimize the stray inductance and the AC losses). Using a multilevel converter for an avionic application with DC Link of 270V would also allow the usage of LV devices with excellent on-state characteristics, still retaining all the advantages of the modular architecture.

This QAB+CHB architecture has already been proposed for solid-state transformer applications [9] and it is shown in Fig. 3. Because only a DC/DC converter with a transformer is present, the system is more compact than a solution where three DC/DC converters are used.

The proposed control of the QAB aims at regulating symmetrical DC link voltages regardless the power transfer. The schematic of the control is presented in Fig. 4, assuming as a reference the phase-shift of port 4. In this way, the phase-shift d_{1-3} are related to the power that is transferred to ports 1-3 to port 4. A PI regulator controls the bus voltage and embeds a droop controller with coefficient R_{v4} . Additional controllers are used to regulate the DC links of the CHB side.

The CHB must control the AC current, the internal cell balancing is not necessary because the QAB is performing the task. Different modulation strategies can be adopted, the



Fig. 2: Quadruple Active Bridge schematic.

of the CHB can still transfer power to the DC bus.

The CHB+QAB solution has several degrees of freedom, because the AC side is three-phase and the QAB can be used in 3-1 (three ports AC and one DC) or in 2-2 (two ports for AC and DC) mode. Fig. 5 shows how the CHB+QAB can be used to realize a three port AC/DC+DC converter, with one AC port and two DC ports. The biggest advantage of this kind of approach is the possibility to connect a generator directly to two bus bars, as in Fig. 6. The internal power sharing of the QAB allows for different power to be distributed to the bus bars.

This solution has several degrees of redundancy:

- The three phase AC/DC is composed of six H bridge with an intrinsic fault tolerant capability.
- Since there are 3 QAB converter, the fault of one QAB does not interrupt the power flow to the DC buses.
- If a generator ceases to function, the QAB still allows for the power exchange between the bus bars, allowing for seamless transition to a post-fault condition.



Fig. 3: A two-port modular smart TRU.

phase-shift PWM allows for a very low Total Harmonic Distortion (THD). Advanced strategies in case of unbalanced power transfer can also be adopted [10]. In the case of a fault in a CHB cell, this can be bypassed and the converter operates normally. In case of a fault of the QAB, the other two phases



Fig. 4: Control of the QAB to balance the DC Links.

Main Engine Aux Power Unit Main Engine



Fig. 6: Example of an hybrid electrical power distribution systems with smart TRU.

This solution replaces the solid-state switches allowing for the virtual connection of the whole EPDS (with benefits in terms of better utilization of the generators) but still guaranteeing the galvanic isolation.

IV. EXPERIMENTAL RESULTS

In order to test experimentally the operation of the STRU, especially under a fault condition in a CHB cell, a singlephase prototype is used. The prototype features three CHB cells and a QAB converter, comprising of the high-frequency transformer. Fig. 7 shows the laboratory prototype and Table I lists the parameters.



Fig. 7: Picture of the proposed STRU.

TABLE I: Experimental parameters

$V_n (V_1, V_2, V_3, V_4)$	270 V
P_n	3 kW
L_1, L_2, L_3	160 uH
L_4	35 uH
L_{eq}	95 uH
C_1, C_2, C_3, C_4	0.4 mF
f_{sw}	20 kHz

Fig. 8 shows the schematic of the experimental setup. A Power Supply is connected to the DC port and a Resistive-Inductive (RL) load is connected to the AC port. If a fault occurs, e.g., short-circuit of the switch S3, the H-bridge outputs zero voltage by disabling switches S2 and S3 and switching on S1. During this transition, the QAB port can still be operational, controlling the voltage. After the fault, it can be switched off and the QAB can be reconfigured into a Triple Active Bridge (TAB). A similar procedure can be adopted in the case of an open-circuit fault.

The condition that has to be analyzed is the post-fault operation of the STRU in terms of having unchanged output voltage and DC output voltage. This experiment is shown in the following figures. Fig. 9 shows the AC current and the overall output voltage of the CHB when a fault happens at the time t = 0 s. The remaining CHB cells increase the duty cycles and the current amplitude is unaffected. A higher ripple appears due to the reduction of the effective switching frequency. Fig. 10 shows that at time t = 0 s the lower cell is bypassed. Fig. 11 shows the particular of the DC Link voltages at the moment of the fault. Although the power consumption changes abruptly, the QAB control still regulates the DC voltage.

Fig. 12 and Fig. 13 shows the waveforms of the QAB during the transition. The top waveforms refers to the cell that increases its loading while the bottom waveforms refers to the excluded cell. These experiments show how the control of the QAB always regulates the DC voltage regardless the output power.

The efficiency of the QAB was measured with the Yokogawa WT1800 with the goal to analyze both the overall



Fig. 8: Schematic of the setup for the experiments. The faulty cell is bypassed by forcing an output zero vector.



Fig. 9: Experimental results. AC current and output voltage of the CHB.

efficiency and the efficiency reduction when the QAB is operating in a heavily asymmetrical mode. As it can be seen from Fig. 14, when only one QAB port is providing the full power and the other two ports keep operating, but with no load. Despite the very asymmetrical operating mode, only a small efficiency deterioration of 0.1 % at 2 kW happens.

V. CONCLUSION

In this paper, a Smart Transformer-Rectifier Unit (STRU) is proposed to replace the standard transformer based TRU and to realize the AC/DC converter for the electrical generators. The redundancy of this solution and the possibility to realize a virtual connection of the DC bus bars via the STRU DC ports make this converter a promising solution to improve the aircraft electrical power distribution system. The reduced voltage level allows for small footprint and high efficiency devices to be used, paving the way for an increase of the power density and fault tolerance at the same time. Experimental



Fig. 10: Experimental results. AC voltage and current of the CHB cells when the first module is excluded.



Fig. 11: Experimental results. DC current and AC voltage of the CHB cells when the first module is excluded.

results show how the control of the STRU is resilient to a fault in the AC side.

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Fig. 12: Envelope of high frequency waveforms of voltage and current of loaded and unloaded cell during the fault simulation.



Fig. 13: High frequency waveforms of voltage and current of loaded and unloaded cell.



Fig. 14: Efficiency measurement of the QAB converter [6].

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